

# **2017 NAITC Conference Kansas City, Missouri**

Show Me Agriculture!

# Drone Technology Takes Flight – In Agriculture!

Presented by the “North Dakota Team”

Food, Land & People Facilitators

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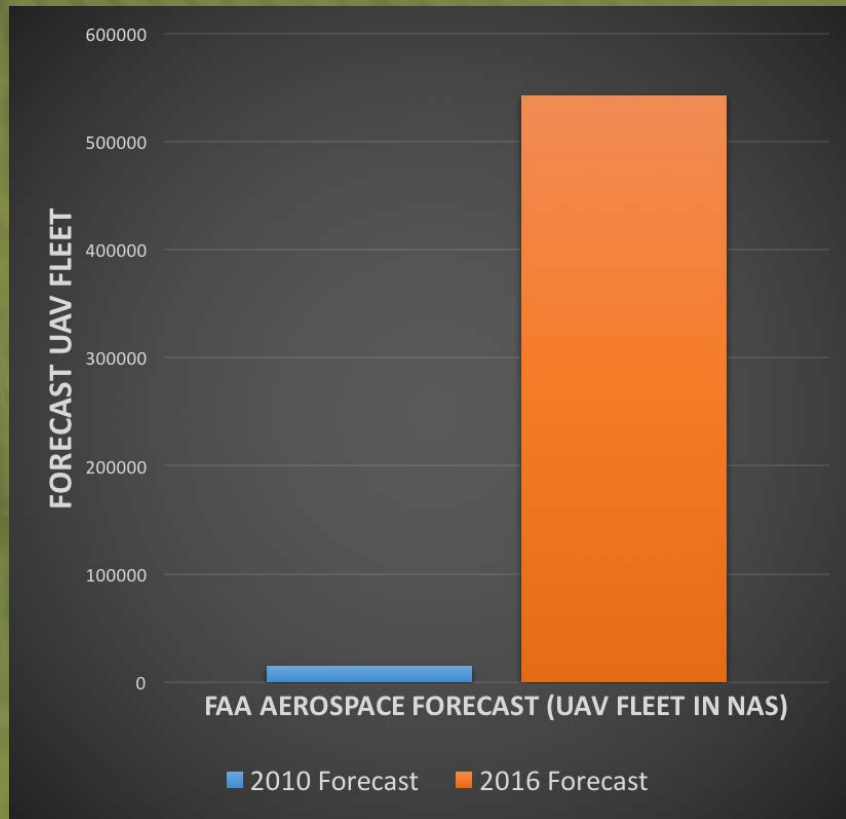
# WHAT IS A DRONE OR AN UNMANNED AERIAL VEHICLE?



- Essentially, a **drone** is a flying robot. Drone is the broad term used to apply to any UAV. Drones may be remotely controlled or can fly autonomously through software-controlled flight plans in their embedded systems, working in conjunction with onboard sensors and GPS.
- “Quadcopter” is a more specific term used to refer to a drone that is controlled by four rotors. These UAVs are always controlled remotely instead of being controlled by a pre-programmed, onboard computer.



# Explosive Consumer Growth!



- ❖ FAA Aerospace Forecast for number of UAV's in consumer hands by 2020 – 2010 predictions compared to 2016 predictions
- ❖ 15,000 estimated number raised to 542,500!?!

The Explosive Growth in the Use of UAV's

**WHERE ARE UAV'S BEING USED?**



An aerial photograph of a large agricultural field during sunset. A green combine harvester is in the lower center, moving from left to right and kicking up a large cloud of dust. The field is divided into long, straight rows of harvested crops. In the background, there are patches of green grass, small ponds, and a distant shoreline under a warm, orange-hued sky.

# Opportunities for STEM Students

- USDA's National Institute of Food and Agriculture estimates there will be some 58,000 high-skilled annual job openings in the food, agriculture, renewable natural resources, and environment fields.
- However, there are an average of 35,400 new U.S. graduates with a bachelor's degree or higher in agriculture related fields
- Let's INSPIRE students by educating them about opportunities in ag related fields and technology....

# Drone Overview

- ❖ Unmanned Aerial Vehicle (UAV).
- ❖ Four main parts of the drone system: platform (aircraft), sensor (camera), target (what is observed), and ground control station (where the person operates the drone).
- ❖ Drones are useful for dull, dirty, dangerous jobs.



# Flight Dynamics

- ❖ Flight Dynamics: The study of performance, stability and control of vehicles flying through the air.
  - Roll: Rotation around the front-to-back axis
  - Pitch: Rotation around the side-to-side axis
  - Yaw: Rotation around the vertical axis
    - ❖ A Propcopter doesn't have wings (blades) or a tail, so it operates mostly on yaw.
- ❖ Awesome website: [AMA Flight School](#)



# Four Forces of Flight

## ❖ Force of Flight:

1. Lift: The force opposite of gravity. Upward force created by airflow under the wing.
  - Lift is different for propcopter vs. planes. Why?
2. Gravity: The force opposite of lift. Causes an object to be pulled downward.
3. Thrust: The force that moves an object through the air.
4. Drag: The force that limits the speed of an object.

# Things that Fly

## Objectives:

- ❖ Learn about the drone platform.
- ❖ Design flying devices to explore forces of flight and flight dynamics.

## Materials:

- ❖ Propcopters
- ❖ Foam plates
- ❖ Scissors
- ❖ Clear tape
- ❖ Pattern
- ❖ Pen
- ❖ Penny



# Drone Discovery- National Youth Science Day 2016

## ❖ How to find the experiment online:

<http://4-h.org/parents/national-youth-science-day/4-h-nysd-2016-drone-discovery/>

## ❖ On the website:

- ❖ Youth and facilitator guide
- ❖ How-to-videos
- ❖ Information on Scratch



# Take Off- Agriculture Challenge

## Community Setting

- Corn field
- Residential suburb
- Farm

## Issue Challenge

- Corn plants are being crowded out by weeds
- A bison escaped from the zoo
- A cow and calf are missing

## Drone Action

- Survey a field
- Take a video

## Group Action

- Observes invasive plants
- Locate the bison
- Locate the cow and calf



# Our Challenge...

- ❖ Your farm is facing a challenge: A missing cow and calf You and your engineering team decide to find out more. Ginger says, “I think drones can help with this!”
- ❖ They suggest using a drone to take a video.
- ❖ Your team locates the missing cow and calf.
- ❖ Success! Your engineering team decides to celebrate by posting the picture the drone took of the cow and calf on Facebook.

## ❖ Discuss:

- ❖ What do you think about your scenario? Does it seem possible? How do you think the drone will help? What does success look like in this scenario?

# Foam Drone

## Objectives:

- Learn how to use the keychain camera.
- Understand remote sensing.
- Design a remote sensing system model to solve the problem.

## Materials

- Foam Glider
- Keychain camera
- SD card
- USB cable
- Computer
- Velcro
- Tape
- Target



# Foam Drone- Team Roles

**\*\*We won't do this part, but this may be an important part to incorporate with youth.**

**Project Manager:** Coordinates work for the team, keeps everyone on task.

**Lead Engineer:** Leads the building process. Takes the lead in assembling the aircraft.

**Flight Engineer:** Repairs the plane.

**Sensor Engineer:** Works with the flight engineer to place the camera, and play the video.

**Product Owner:** The voice of the customer the engineering team is working with.

**Design Engineer:** Responsible for graphic design. Decorates the aircraft.

**Documentarian:** Keeps records of the design process.

**Marketing Specialist:** Takes pictures and posts about progress in order to communicate about STEM to the public.

**Data Manager:** Transfers video data from the camera to the computer for viewing.

# Code Copters

## Objectives:

- Sign up for Scratch account
- Find NYSD 2016 Scratch program:  
<https://scratch.mit.edu/projects/116115355/>
- Explore remote sensing principles through basic coding.
- Practice writing and using specific code.
- Use a coordinate system to program a drone flight pattern.

## Materials:

- Code Copters IRL: Masking tape, command cards
- Code Copters: Computer with internet access



# Code Copters- Team Roles

## Flight Plan Engineer

- ❖ Thinks about the best strategy to move the drone.

## Programmer

- ❖ Take the pathway from the flight engineer and creates the code to make the drone move.

## Prototype Engineer

- ❖ Reads the code to the drone. Reports back about if the code needs any changes.